

Linear lambda-calculus is linear

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Motivation

Linear Logic



Linear Algebra

Linearity expressed by its models (linear maps)

Lambda-calculus is the language of functions

Linear lambda-calculus is the language of **linear** functions

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Linear Logic



Linear Algebra

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Lambda-calculus is the language of functions

Linear lambda-calculus is the language of linear functions

But, how?

Linear in the algebraic sense...

$$f(v + w) = f(v) + f(w)$$

$$f(a.v) = a.f(v)$$

This is not easily expressible with lambda-terms

Interstitial rules

Addition and multiplication by scalar

$$\frac{\Gamma \vdash A \quad \Gamma \vdash A}{\Gamma \vdash A} \text{ sum}$$

$$\frac{\Gamma \vdash A}{\Gamma \vdash A} \text{ prod}$$

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Now some proofs cannot be reduced, e.g.

$$\frac{\frac{\frac{\pi_1}{\Gamma \vdash A} \quad \frac{\pi_2}{\Gamma \vdash B}}{\Gamma \vdash A \wedge B} \wedge_i \quad \frac{\pi_3}{\Gamma, A \vdash C}}{\Gamma \vdash C} \text{ prod } \wedge_e$$

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Commute sum either with the intro or with the elim

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We chose to commute with the introduction as much as possible

The \mathcal{L}^S -calculus

Intuitionistic linear logic connectives

	Mult	Add	PL
Truth	1	\top	\top
Falsehood	—	0	\perp
Implication	\multimap	—	\Rightarrow
Conjunction	\otimes	$\&$	\wedge
Disjunction	—	\oplus	\vee

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Proof-terms

$$\begin{aligned}
 t = x \mid t \multimap t \mid a \bullet t \mid a \star \mid \delta_{\top}(t, t) \mid \delta_{\perp}(t) \\
 \mid \lambda x.t \mid tt \\
 \mid \langle t, t \rangle \mid \delta_{\wedge}^1(t, x.t) \mid \delta_{\wedge}^2(t, x.t) \\
 \mid \text{inl}(t) \mid \text{inr}(t) \mid \delta_{\vee}(t, x.t, y.t)
 \end{aligned}$$

a is scalar from some structure $(\mathcal{S}, +, \times)$.

Some deduction rules

$$\begin{array}{c}
 \frac{}{\vdash a \star : \top} \text{T-i}(a) \quad \frac{\Gamma \vdash t : \top \quad \Delta \vdash u : A}{\Gamma, \Delta \vdash \delta_{\top}(t, u) : A} \text{T-e} \\
 \\
 \frac{\Gamma \vdash t : A \quad \Gamma \vdash u : A}{\Gamma \vdash t \multimap u : A} \text{sum} \quad \frac{\Gamma \vdash t : A}{\Gamma \vdash a \bullet t : A} \text{prod}(a)
 \end{array}$$

$$\delta_{\top}(a \star, t) \longrightarrow a \bullet t$$

$$a \star \multimap b \star \longrightarrow (a + b) \star$$

$$(\lambda x.t) \multimap (\lambda x.u) \longrightarrow \lambda x.(t \multimap u)$$

$$a \bullet b \star \longrightarrow (a \times b) \star$$

$$a \bullet \lambda x.t \longrightarrow \lambda x.a \bullet t$$

Vectors and Matrices

Definition (The set \mathcal{V})

$\top \in \mathcal{V}$, If $A, B \in \mathcal{V}$, $A \wedge B \in \mathcal{V}$

$A \in \mathcal{V}$, $d(A) = \text{number of } \top$

Definition (One-to-one correspondance)

$A \in \mathcal{V}$ with $d(A) = n \iff \mathcal{S}^n$

$\vdash t : A$ (t irreducible) \longrightarrow unique vector $\underline{t} \in \mathcal{S}^n$

$\mathbf{v} \in \mathcal{S}^n \longrightarrow$ unique irreducible proof $\bar{\mathbf{v}}^A$

Example

$$\underbrace{\langle \langle a.\star, b.\star \rangle, c.\star \rangle}_{(\top \wedge \top) \wedge \top} \leftrightarrow \underbrace{\begin{pmatrix} a \\ b \\ c \end{pmatrix}}_{\mathcal{S}^3}$$

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Lemma (Some properties)

$$\underline{t} + \underline{u} = \underline{t} + \underline{u}$$

$$\underline{a} \bullet \underline{t} = \underline{a} \underline{t}$$

Vectors and Matrices

Definition (The set \mathcal{V})

$$T \in \mathcal{V}, \quad \text{If } A, B \in \mathcal{V}, \quad A \wedge B \in \mathcal{V}$$

$$A \in \mathcal{V}, \quad d(A) = \text{number of } T$$

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Lemma (Some properties)

$$\underline{t} \oplus \underline{u} = \underline{t} + \underline{u}$$

$$\underline{a} \bullet \underline{t} = \underline{a}t$$

Theorem (Matrices)

$A, B \in \mathcal{V}$ with $d(A) = m$ and $d(B) = n$ $M \in \mathcal{S}^{m \times n}$
 Then, there exists $\vdash t : A \Rightarrow B$ such that for all $\mathbf{v} \in \mathcal{S}^m$
 $\underline{t\bar{\mathbf{v}}^A} = M\mathbf{v}$

Example

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \longrightarrow \lambda x. (\delta_{\wedge}^1(x, y. \delta_T * (y, \langle a.\star, b.\star \rangle)) \oplus \delta_{\wedge}^2(x, z. \delta_T * (\langle c.\star, d.\star \rangle)))$$

Linearity

The main theorem

Theorem (Linearity)

*Let A be any proposition, $B \in \mathcal{V}$, $\vdash t : A \Rightarrow B$, and
 $u, v \in A$, then*

$$t(u \oplus v) \equiv (tu) \oplus (tv) \qquad t(a \bullet u) \equiv a \bullet (tu)$$

Linearity

The main theorem

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Let A be any proposition, $B \in \mathcal{V}$, $\vdash t : A \Rightarrow B$, and $u, v \in A$, then

$$t(u \mathbf{+} v) \equiv (tu) \mathbf{+} (tv) \qquad t(a \bullet u) \equiv a \bullet (tu)$$

It does not extend directly to arbitrary B :

Let $t = \lambda x. \lambda y. (yx) : \top \Rightarrow (\top \Rightarrow \top) \Rightarrow \top$

$$t(1. \star \mathbf{+} 2. \star) \longrightarrow^* \lambda y. (y3. \star)$$

$$(t1. \star) \mathbf{+} (t2. \star) \longrightarrow^* \lambda y. ((y1. \star) \mathbf{+} (y2. \star))$$

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Corollary

Let $A, B \in \mathcal{V}$ with $d(A) = m$, $d(B) = n$ and $\vdash t : A \Rightarrow B$.
Then, the map F from S^m to S^n , defined as $F(\mathbf{u}) = \underline{t\bar{u}}^A$ is linear.

Summarizing

- ▶ We presented the \mathcal{L}^S -logic, an extension of a fragment of **intuitionistic linear logic** with two **interstitial rules** and its commuting rules to recover cut elimination.
- ▶ We have shown that its proof-language can express matrices in $\mathcal{S}^{m \times n}$
- ▶ Moreover, we have shown that every term of type $A \Rightarrow B$, with $B \in \mathcal{V}$ is linear in the algebraic sense.

In the paper, but I got no more time for this...

- ▶ Extending the \mathcal{L}^S -logic with the \odot operator, we get a quantum programming language (see [Díaz-Caro & Dowek ICTAC 2021]).